



2. Resistive Strain-strain Gauge-gauge

Resistive potentiometers were described in the previous section, and they They measure involved displacement that was being measured by potentiometry but without altering the properties of the used-resistance used. However, In contrast, resistive strain gauges measure displacement with changes to a resistance that result resulting from the transducer element being strained by a the displacement (National Instruments, 1998). A fractional change in length defines the strain (Figure 3; Equation 5), as shown in Figure 3.

Commented [CP1]: In the remainder of the text, the headings are in "sentence case," which is where only the first word and proper nouns are capitalized. I changed this heading to ensure a consistent style.

Commented [CP2]: Paragraph indentation was added here for consistency with the rest of the document.

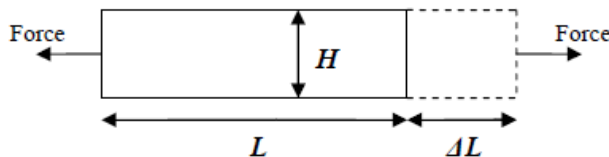


Figure 3. Definition of strain as a fractional change in length (Adapted from National Instruments, 1998).

$$\varepsilon = \frac{\Delta L}{L} \quad (5)$$

There are various designs of resistive strain gauge designs (National Instruments, 1998). A piezoresistive strain gauge is a semiconductor device where the resistance varies nonlinearly

with strain ~~is called a piezoresistive strain gauge~~. The most commonly used ~~design of for a~~ resistive strain gauge is the bonded metallic strain gauge, ~~that which~~ consists of fine wire or metallic foil arranged in a grid pattern, ~~+~~. This ~~design~~ maximizes the amount of metal subjected to parallel strain. The ~~is~~ grid is bonded onto a thin “carrier” backing, and ~~this the~~ carrier is attached to the ~~subject being measured~~ ~~measured subject~~. ~~So~~ ~~Therefore~~, any strain experienced by the test subject is transferred to the strain gauge, ~~this producing~~ ~~a response of a linear change in~~ ~~electrical resistance~~ ~~linear change in electrical resistance response~~.

Gauge factor (GF) is a parameter ~~which that expresses~~ ~~defines~~ a strain gauge’s sensitivity to strain. It ~~means~~ ~~is expressed as~~ the ratio of fractional change in electrical resistance to ~~the~~ fractional change in length (strain):

$$GF = \frac{\Delta R / R}{\Delta L / L} = \frac{\Delta R / R}{\epsilon} \quad (6)$$

For metallic strain gauges, GF ~~mostly has a value of -2~~ ~~values are typically around~~ ~~approximately~~ two.

Commented [CP3]: As a rule, numbers below 10 are spelled out unless the number is associated with a unit.

~~Because~~ ~~As~~ most strain measurements involve very small ~~quantities of strains~~, and ~~the~~ GF is ~~approximately two~~ ~~-2~~, ~~tiny small~~ changes in electrical resistance ~~are generally small~~ ~~usually result~~ (National Instruments, 1998). ~~To measure these small resistance changes, you should use strain gauges in a bridge configuration with a voltage or current excitation source~~ ~~Strain gauges are used in a bridge configuration with a voltage or current excitation source~~

to measure these small resistance changes. A Wheatstone bridge (Figure 4) is composed consists of 4-four resistive arms plus-with an excitation voltage (V_{ex}) applied across the bridge.

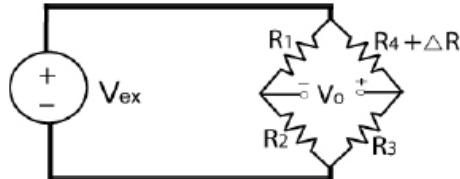


Figure 4. Wheatstone bridge (Adapted from National Instruments, 1998).

Output The output voltage of the bridge, V_o , can be calculated-calculated in-using Equation 7:

$$V_o = \left[\frac{R_3}{R_3 + R_4} - \frac{R_2}{R_1 + R_2} \right] \cdot V_{ex} \quad (7)$$

~~Drawbacks to strain~~ Strain gauges suffer from several drawbacks, include-including the facts that great-precision is-required during the manufacturing process, and that moisture-effects can-e-reduce-reduction in the long-long-term reliability of measurements due to moisture effects unless the strain gauge is hermetically sealed (Measurements Group, 2001).

Strain gauges have a-number-of-several benefits (Measurements Group, 2001).-They are typically-including their typically small size and have-a-low mass. They are also durable and

Commented [CP4]: I would suggest moving the drawbacks after the benefits to place more emphasis on the benefits of strain gauges.

Commented [CP5]: I combined these two paragraphs because they share a common focus (highlighting the characteristics of strain gauges). Paragraphs only need to be divided when you are describing different subjects.

Additionally, having the drawbacks and benefits in the same paragraph allows the reader to observe the contrasting features more directly. Ideas within a given paragraph are assumed to be connected, so your audience will already be in the mindset to connect these ideas.

~~shock-resistant due to have a their~~ bonded construction and ~~a lack of of~~ moving parts, ~~and this makes them durable and shock resistant~~. Linearity is ~~great excellent for over~~ a ~~large wide~~ range of strains, and their measurements are stable over time. Strain gauges are also ~~fairly reasonably cheap inexpensive~~.

Omega Engineering, Inc. (Stamford, CT) offers many models of strain gauges ~~which that~~ have measurement ranges appropriate for human kinematic studies. These gauges are ~~cheap inexpensive~~ and long-lasting, with ~~a~~ fatigue limit exceeding ~~10000000 ten million~~ cycles (Omega Engineering Inc., 2007). Their SGD series of gauges ~~has have~~ a ~~gauge factor GF~~ of $2.0 \pm 5\%$.

~~Applications that s~~Strain gauges have been used to measure ~~include human movements,~~ ~~such as S~~shoulder tension (Hughes et al., 1999) and ankle strain (Vandervoort et al., 1992) ~~include the human movement applications that strain gauges have been used for.~~

3. Inductive displacement transducer

~~This Inductive type of~~ displacement transducers ~~type employs methods using uses~~ ~~methods using~~ the ~~inductance~~ variation of ~~inductance of~~ single coils or the mutual inductance of two coils (Cobbold, 1974). The first ~~type of methods are is~~ based on inductance change in one coil ~~either through a changes in the its~~ geometry ~~of the coil or in the properties of~~ magnetic path ~~properties~~. The second ~~type of systems,~~ which involves ~~2 two~~ or more coils, uses a change in mutual coupling ~~which resultings~~ from relative coil displacement or ~~from the movement of a~~ coupling core ~~movement~~.

~~Among the various types of inductive displacement transducers, t~~The ~~linear variable~~ differential transformer (LVDT) is ~~one of among~~ the most popular ~~inductive displacement~~

Commented [CP6]: Once an acronym has been introduced into the text using its expanded form, only the acronym form is needed.

Commented [CP7]: The indentation was removed here for consistency with the preceding section.

Commented [CP8]: This should not be capitalized because it is not a proper name.

transducer types (Cobbold, 1974). One reason ~~that for~~ the LVDT's is-popularity is its large output for small movements. ~~The LVDT is made up of~~ consists of 3 coils: one primary coil and two identical secondary coils ~~that are the same~~. It has a shifting core that can alter the coupling between the 3-three coils, ~~this-producing es~~ the output displacement signal (Figure 5).

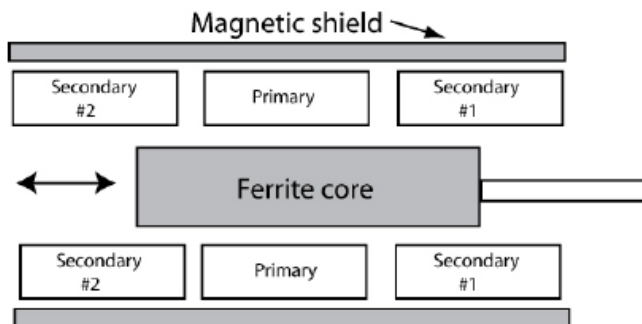


Figure 5. Construction of a linear variable differential transformer ~~(LVDT)~~. Displacement is measured by ~~the~~ It's movable core's interaction with the 3-three coils ~~makes a measures of the displacement~~. (Adapted from Cobbold, 1974.)

In general, v Voltages in the 1—10 V range are generally used, and commercial LVDT's have sensitivities of approximately 0.5—2.0 mV per 0.001 cm displacement per volt of excitation. The ~~RDP Group (Pottstown, PA) makes their~~ ACT LVDT Displacement Transducer, produced by the ~~this RDP Group (Pottstown, PA)~~, featuring inges es a measurement range up to ± 470 mm, great excellent accuracy, ~~sensitivity of~~ 700 mV/V sensitivity, and infinite resolution (RDP Group: Menu of Displacement Transducers, 2007). Their ACT8000C model, ~~which~~ has a range of ± 200 mm and ~~costs~~ \$635 (Socie, 2007). LVDTs are many times often used in-for

Commented [CP9]: Please check these edits to confirm that your intended meaning has not been altered. From the original sentence, it was unclear if only the secondary coils were the same or if all three of them were the same.

Commented [CP10]: I deleted "LVDT" here. It is unnecessary to include the acronym in the figure legend unless you are going to use it again in the legend.

Commented [CP11]: Does "ACT" have an expanded form, or is this the product's name? If it has an expanded form, it would be useful to include that here.

Commented [CP12]: Note that this reference does not appear in the reference list.

physiological ~~measurements of~~ displacement, force, and pressure measurements (Cobbold, 1974).

4. Capacitive displacement transducer

Capacitive displacement transducers function ~~by the fact~~ on the principle that a change in capacitance is proportional to the change in displacement of the object ~~that is~~ being measured (Norton, 1989). Displacement ~~is able to~~ can be converted to an electrical output using the capacitor plate separation distance, ~~the plate area~~ dependence, ~~of capacitance on plate area~~ and the permittivity of the medium between the capacitor plates (Cobbold, 1974). While ~~it is an issue that~~ all capacitive transducers ~~face the problem~~ have the disadvantage that displacement ~~makes~~ causes relatively small changes in capacitance, ~~by the use of particular~~ using specialized circuit techniques ~~allows these transducers can to have~~ results in ~~great~~ excellent accuracies and sensitivities ~~≤ of~~ 10^{-12} cm ~~or better~~ (Sydenham, 1972).

If ~~we ignore~~ the effects of electrical field fringing at the plate edges are ignored, capacitance is given by Equation 8:

$$C = \frac{\epsilon A}{d} \quad (\text{in Farads}) \quad (8)$$

where A is the plate area (in cm^2), d is the plate separation (in cm), and ϵ (in F/cm) is the ~~mediums~~ permittivity of the medium separating the plates.

A basic capacitive displacement transducer is [shown](#) in Figure 6, [where](#) C represents a capacitorive plate, and x is the distance between plates.

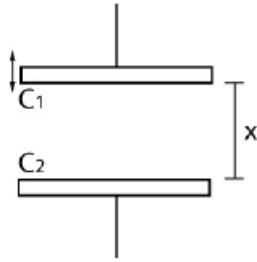


Figure 6. Basic design of a [capacitive](#) displacement transducer. (Adapted from Cobbold, 1974.)

The [direct current \(DC\)](#) polarizing circuit [is shown in Figure 7](#) and it is one of the simplest circuits that [is able to can](#) respond proportionally to the displacement of such a parallel-plate capacitor transducers ([Figure 7](#)).

Commented [CP13]: This abbreviation should be defined and also capitalized.

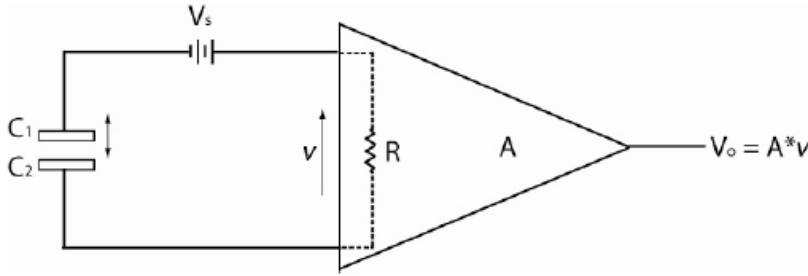


Figure 7. DC-polarized ~~capacitive~~capacitive displacement transducer. V_s is the voltage source, C represents a capacitor plate, R is resistance, v is the voltage across the resistance, A is the ~~amplifier~~amplifier gain, and V_o is the output voltage. (Adapted from Cobbold 1974.)

For this system, the output voltage v is given by Equation 9:

$$v = \frac{VC_0R}{d} \left(\frac{j\omega}{1 + j\omega C_0R} \right) x_0 e^{j\omega t} \quad (9)$$

Wwhere d is the plate separation distance, $x_{0\theta}$ is the sinusoidal plate displacement

~~aplitude~~amplitude, $C_0 = (\epsilon A)/d$, and V is the DC-polarization voltage. If $\omega C_0 R \gg 1$, Equation

9 becomes:

$$v = \frac{Vx_0 \sin \omega t}{d} \quad (10)$$

Commented [CP14]: Note that Fig. 7 lists V_o as the output voltage.

Commented [CP15]: Note that j , ω , t , and R in Eq. 9 have not been defined here.

By inspection of Equations 9 and Equation 10, we see that $\frac{1}{\omega C}$ indicates that higher frequencies the system's response is proportional to the inverse displacement at higher frequencies. However, for the response is reduced at lower frequencies lower frequencies the response is reduced, and becomes zero if when $\omega = 0$. This system's lack of DC response of this system is a concerning when measuring many physiological quantities.

To solve this problem can be solved by using a we should use the transducer as the feedback component of a high-gain operational amplifier, since The transducer transforms the problematic inverse displacement -vs.-capacitance relation now to becomes a simpler linear output voltage -vs.-displacement relation that we can work with. The circuit diagram of this such a different system is shown in Figure 8.

Commented [CP16]: Please confirm that 'proportional to the inverse displacement' matches your intended meaning.

Commented [CP17]: I combined these paragraphs because they share related content (addressing the DC response issue).

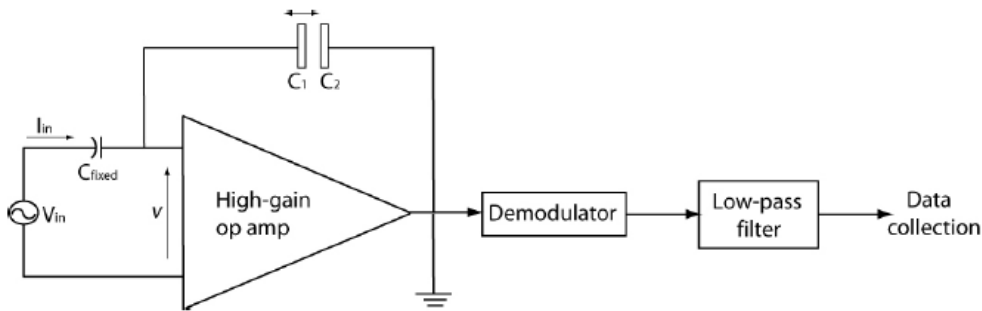


Figure 8. ~~System diagram~~ Diagram of a linear displacement measurement system using ~~capacitive~~ capacitive sensing. (Adapted from Cobbold, 1974.)

As an example One such linear displacement measurement system, the Sensagap capacitive displacement sensor, ~~from the RDP Group~~ can be ~~acquired~~ used for kinematic measurements in

over a variety of measurement ranges ~~that are able to be used for kinematic measurements.~~ It features a linearity of $\pm 0.5\%$ of full-scale or better and can withstand shocks up to 20.g (RDP Group: Sensagap Capacitive Displacement Transducer, 2007).

References:

Cobbold RSC. *Transducers for Biomedical Measurements: Principles and Applications*. New York: John Wiley & Sons. 1974.

Hughes CJ, Hurd K, Jones A, Sprigle S. Resistance Properties of Thera-Band Tubing during Shoulder Abduction Exercise. *J Orthop Sports Phys Ther*, Jul 29(7): 413—20, 1999.

National Instruments. ~~(1998)~~ Strain Gauge Measurement – A Tutorial. Application Note 078, 1998. http://www.eidatics.com/Downloads/Refs-Methods/NI_Strain_Gauge_tutorial.pdf

RDP Group, Sensagap Capacitive Displacement Transducer. 2007.
<http://www.rdpe.com/us/sg.htm>

Vandervoort AA, Chesworth BM, Cunningham DA, Rechnitzer PA, Paterson DH, Koval JJ, An Outcome Measure to Quantify Passive Stiffness of the an Ankle. *Can J Public Health*, Jul—Aug; 83, Suppl 2: S19—23, 1992.

Commented [CP18]: As a referencing style was not specified, I edited the reference list for consistency only.